

# VACUUM DISC STABILIZER PD-375 FULLY AUTOMATIC TURNTABLE



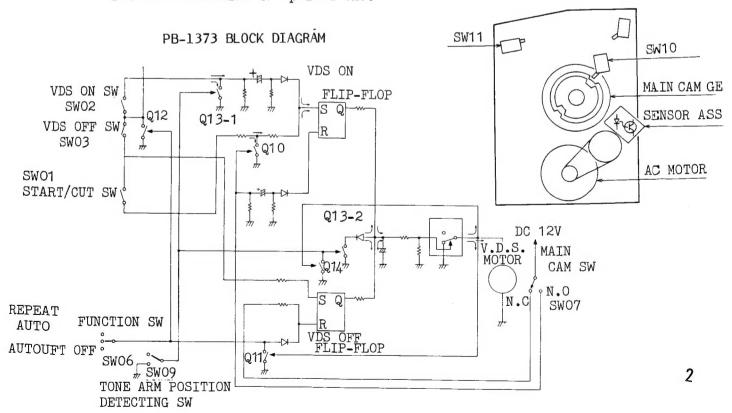
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SPECIFICATION			
,		OUTT TIMENO CHART	
FULI 33 r	L AUTO MECHA. CIR .p.m.	CUIT TIMING CHART  45 r.p.m.	
AC Motor Start		tor Start	
Terminal No.4	Mecold Flid		12V — 0
			0 12V
IC Pin 1,2			o
IC Pin 3,5,6,9	7		12V
10 PIN 9,9,0,9			0 12V
IC Pin 4	Λ		0
TO D: 0	$\Gamma$		12V
IC Pin 8 ]			0
IC Pin 10			12V 0
			12V
IC Pin 12			0
IC Pin 13	Λ		12V
10 1111 19			0
IC Pin 11			12V 0
			M.C
SW10 Common			N.0
TRO1			12V
			ON
F.A.M. AC Moter			OFF

#### EXPLANATION ABOUT FULL-AUTO MECHANISM

- (1) Normal (Power SW ON only in Play)
  Only NAND Gate input 12 is different between 33 r.p.m. and 45 r.p.m.
- (2) Put on START/CUT Button
  NAND Gate output 10 shall be OV, and TRO1 and AC motor shall be ON.
  As soon as AC motor has been ON, SW 10 shall rotate until TRO1 becomes OFF after SW 10 on the cam at the final stage has again turned over and the cam at the final stage has turned over half.
- (3) Record End
  As inside most diameters of LP and EP Groovesare different each other,
  operation is also different (Its change can be done by individual r.p.m.)
  - 33 r.p.m. When the slit of Rester Lever comes into Sensor Assembly and the photo transistor becomes ON by L.E.D. light, NAND Gate output 11 shall be ON and AC motor Shall begin to rotate.
  - When the slit of Rester Lever comes into Sensor Assembly with a photo transistor's being ON and the tonearm reaches the inside most with the slit's shutting off L.E.D. light and eventually the photo transistor's being OFF, NAND Gate output 10 shall be OV and AC motor begins to rotate. (On this occassion when the tonearm returns, the slit of Rester Lever again passes through Sensor Assembly and the above mentioned signal shall be input. However, it is not directly related since AC motor is in operation by SW 10.)
- (4) Repeat
  When the tonearm returns to the armrest in REPEAT mode, 12V shall be loaded to the 6P connector by SW 11 and same operation shall be made as in case of pressing START/CUT button.

REMARKS: As mentioned above be careful for any light from outside to come especially into Sensor Assembly when you are repairing since this fll-auto mechanism is optical one.



# D-375

## EXPLANATION ABOUT TRANSISTOR'S

#### Q 10 2SC945

When the rotation started by depressing the "Start/Cut" button after the suction by V.D.S. button, this transistor works to cancel the set signal to FLIP-FLOP circuit of "V.D.S. on ".

---This prevents the mis-suction when the suction operates again once already sucked.

#### Q 11 2SC945

When the mode is set at "REPEAT", the reset signal comes into the V.D.S. off FLIP-FLOP circuit. While the V.D.S. motor is rotating, this transistor operates to cancel this very reset signal until the motor stops rotating by the reset signal coming from SW-O7 at the main cam.

---When the mode is set at "REPEAT" while V.D.S. motor is rotating, no problem to activate "V.D.S. on ". But when the "V.D.S. off" is depressed, V.D.S. motor stops rotating on the way, and the platter is locked. This transistor was adopted to avoid this trouble.

While the reset signal of V.D.S. off FLIP-FLOP circuit is to delete memory of V.D.S. off.

## Q 12 2SC945

This works to cancel DC 12V fed into V.D.S. switch at the "REPEAT" mode.
---This transistor is used so that the V.D.S. on/off switch should not operate at
"REPEAT" mode.

## Q 13-1 2SC945

This operates to cancel not the set signal to be fed to V.D.S. off FLIP-FLOP circuit but the set signal to V.D.S. on FLIP-FLOP circuit except in the case that the tonearm is put on the arm rest position by the tonearm position detecting switch 09.

## Q 13-2 2SC945

This operate to cancel the output coming from "V.D.S. on/off "FLIP-FLOP circuit so that the V.D.S. motor should not rotate except when the tonearm is at the arm rest by the tonearm detector switch 09.

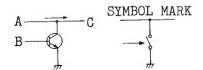
While when the "V.D.S. off "FLIP-FLOP circuit is set on, the V.D.S. operation starts after the tonearm get back to arm rest position.

---This transistor is adopted so that the platter should not be mechanically locked even if "V.D.S. on/off" button is switched on while playing.

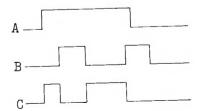
## Q 14 2SC945

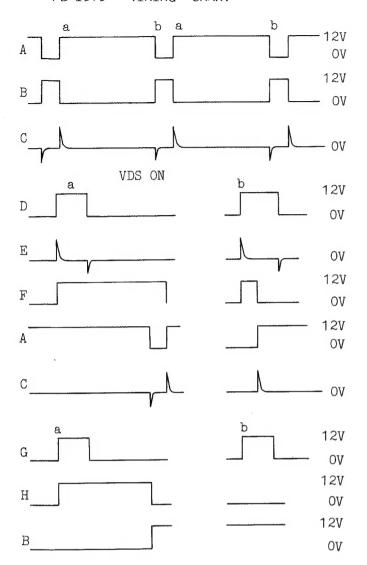
When the tonearm left from the arm rest, the output of V.D.S. on/off FLIP/FLOP circuit is cancelled by Q 13-2. While the tonearm is placed at the arm rest, V.D.S. operation starts, and even if the tonearm left the arm rest before the V.D.S. operation completes, this transistor works to cancel this blocking signal until the V.D.S. operation is achived.

MUTING CIRCUIT (CANCEL CIRCUIT)

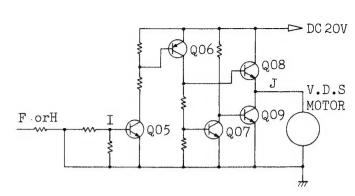


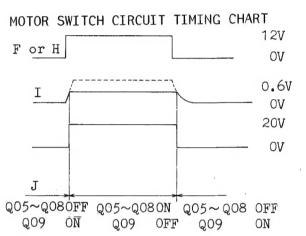
MUTING CIRCUIT TIMING CHART



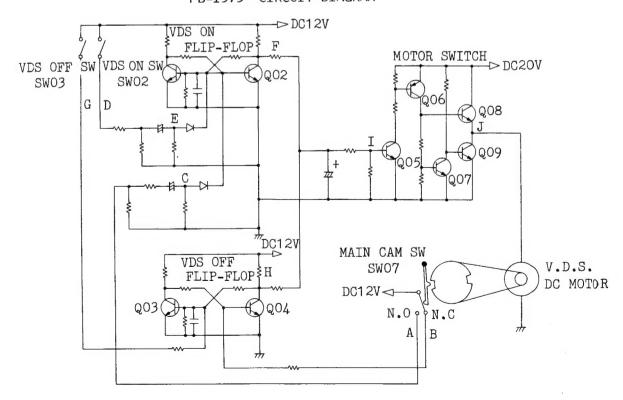


## MOTOR SWITCH CIRCUIT





## PB-1373 CIRCUIT DIAGRAM





### FULL-AUTO MECHANISM ALIGNMENT PROCEDURES

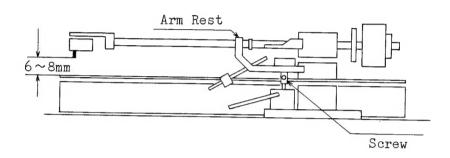
The re-alignment may be required due to the probable deviation in the measurements of the cartridge and disc employed although the complete alignment is already made at the factory side.

(1) Height adjustment of Arm-Lifter

a. Set the disc sucked and put the unit into the playback mode.

b. Loosen the fixing screw for arm-lifter, and adjust the height so that the clearance between the stylus tip and surface of the disc could be procured by about 6--8mm.

Remarks: Proceed this alignment so that the tone-arm should not be hooked by the arm-rest.

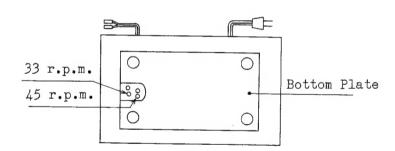


(2) Lead-In Adjustment

a. Obtain the playback mode, and press the Start/Cut switch.

b. Insert the (-) driver from the holes as illastrated in the drawing, and adjust the Lead-In position by rotating the eccentric pin.

33 r.p.m. and 45 r.p.m. can be adjusted separately.

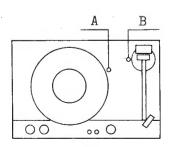


(3) Lead-Out Adjustment

a. Insert the (+) driver from the (A) as depicted, and loosen the screw for the sensor assembly.

b. Insert the (-) driver from the hole (B) as shown in illustration, and adjust the Lead-Out position by moving the position of sensor assembly.

c. After adjustment, fasten the same screw explained in the step (3)-a.

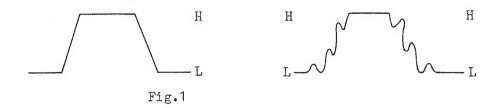


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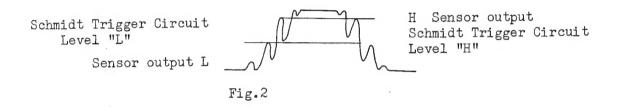
## PD-3

## FULL-AUTO MECHANISM CIRCUIT ALIGNMENT RROCEDURES

There happen to be eccentric record discs among those which are available in markets and in case these eccentric ones are used for playing, the wave form will be as per Fig. 1 when the rester lever slit passes through the light axis of the sensor.



When eccentricity is remarkable, the wave form reads as per Fig. 2 and mis-operation shall be caused as for EP discs.



As return action is made on EP discs when output of schmidt trigger circuit comes to be "L" from "H", mis-operation shall be caused at the portion of the enlarged curve in Fig. 2.

So, prevent from mis-operation, make the hysterisis as wide as possible and adjust output level of the sensor to it.

Widening of the hysteresis in schmidt trigger circuit will be efective to prevention of outcoming noises, etc.

Adjustments of the hysteresis and output level of the sensor are made respectively by the VRO2 and VRO1 as far as the present circuit is concerned.

In the actual procedures firstly adjust the hysteresis and secondly output level of the sensor.

The hysteresis is not always same since threshold value of IC's varies depending on IC's to be used.

So, at first adjust "H" level of schmidt trigger circuit to (x-0.8)V by the VRO2 when output of the sensor is "H" (saturated state, provided to be xV), and at this point "L" level (provided to be yV) of schmidt trigger circuit shall be decided.

Secondly adjust "L" level of output of the sensor to (y-0.6)V by the VRO1.

Above is all for adjustment.

Remarks: As to "H" level difference by 0.8V is made between threshold values of the sensor output and schmidt threshold, and as to "L" level difference by 0.6V between the threshold values. Those values are decided in consideration of changes in temperature, humidity and time process and other drifts as well.

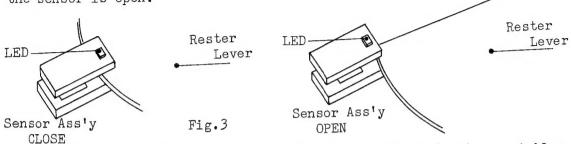


## P.C.B. ALIGNMENT PROCEDURES

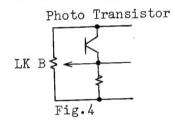
Set voltage for adjustment at 11.5 +0.1V with use of an EP disc and prevent the sensor from receiving external light.

1. Adjustment of the VRO2 (adjustment of the hysteresis in schmidt trigger circuit).

a. Make preliminary adjustment of the VRO2 not to make I.C. No.4 "H" from "L" when the sensor is open.



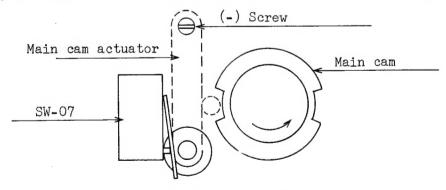
b. Separate output of the sensor as per the Fig.4 below and put a variable resistor externally to give output of the sensor voluntarily.



- c. Measure "H" of output of the sensor (provided to be V ) at the foregoing step a and give voltage of (V -0.8V) at the foregoing step b.
- d. At the foregoing step c adjust the VRO2 to make I.C. No.4 "H" from "L".
- e. Separate the external variable resistor.
- 2. adjustment of the VRO1
  - a. Make preliminary adjustment of the VRO1 not to make I.C. No.4 "L" from "H" when the sensor is made close from open.
  - b. Adjust the VRO1 until I.C. No.4 becomes "L" from "H" when the sensor is made open from close. At this time read out output of the sensor and adjust the VRO1 to make the output -0.6V right at the moment when I.C. No.4 has becomes "L" from "H".

## ADJUSTMENT OF SW-07 (Main Cam SW)

This alignment is needed in the "play" mode when the charge lever cannot be opened sufficiently or the lever is going to shut again causing irregular noise or preventing the platter from turning due to the touch of lever shaft to the platter.



As the pivot of the main cam actuator is eccentric, you can change the timing of the SW-07 by turning the pivot with a (-) screw driver.

Adjust the main cam actuator so that the motor can stop when the charge lever is in the at most open status by pushing the V.D.S. on switch (SWO2).

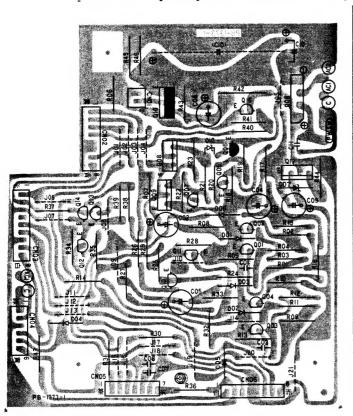
However, as the pivot of main cam actuator plays the circular movement, there are two points having the same timing between the main cam and main cam actuator.

Be sure of choosing the very position which pushes the SW-07 more than the other. After adjustment, do not forget to put glue.

## PB-1373-1 PARTS LIST

Remarks

Capacitor: My...Mylar, El...Electrolytic, Ce...Ceramic



tic, C	eCera	mic
Symbol No.	Stock No.	Description
(Tran	sistor)	
Q01	TR0029	2SC945
Q02	TR0029	2SC945
Q03	TR0029	2SC945
Q04	TR0029	2SC945
Q05	TR0029	2SC945
Q06	TR0320	2SA992
	TR0029	2SC945
Q08	TR0047	2SD235 or 2SD880
Q09	TR0047	2SD235 or 2SD880
Q10	TR0029	2SC945
Q11	TR0029	2SC945
Q12	TR0029	2SC945
1	TR0029	2SC945
	TR0029	2SC945
- ·	TR0029	2SC945
Q16	TR0228	2SB435 or 2SB596
Q17	TR0047	2SD235 or 2SD880
(Diode		
D01	TD0214	Silicon US1035
D02	TD0214	Silicon US1035
D03	TD0214	Silicon US1035
D04	TD0214	Silicon US1035
D05	TD0001	Silicon 1S4001
D06	TD0214	Silicon US1035
D07	TD0027	Zener WZ-120
D08	TD0139	Bridge SIVB20
	1	

					D08	TD0139	Bridge	SIVB20	
Symbol	Stock	Dog	cription	,					
No.	No.	Des	CITP CIOI				1		
(Capac	citor)								
CO1	CK0157	0.04 uF	25WV	Ce	C07	CK0157	0.04 uF	25WV	Се
C02	CE1749	0.47 uF	50WV	El	C08	CE1 703	20 uF	6.3WV	El
CO3	CK0157	0.04 uF	25WV	Ce	C09	CE1 720	47 uF	16WV	El
CO4	CE1 718	22 uF	1 6WV	El	C10	CE1821	3300 uF	25WV	El
CO5	CE1749	0.47 uF	50WV	El	C11	CQ1 325	0.01 uF	50WV	My
C06	CK0157	0.04 uF	25WV	Ce	<u></u>				
	on Resis					T	1	. / 22 -	
RO1	RD0455	8.2K	1/3W		R25	RD0455	8.2K	1/3W	
R02	RD0455	8.2K	1/3W		R26	RD0447	39K	1/3W	
RO3	RD0445	56K	1/3W		R27	RD0453	12K	1/3W	
RO4	RD0447	39K	1/3W		R28	RD0455	8.2K	1/3W	
R05	RD0452	1 5K	1/3W		R29	RD0446	47K	1/3W	
R06	RD0445	56K	1/3W		R30	RD0449	27K	1/3W	
RO7	RD0457	5.6K	1/3W		R31	RD0449	27K	1/3W	
RO8	RD0445	56K	1/3W		R32	RD0455	56K	1/3W	
R09	RD0455	8.2K	1/3W		R33	RD0445	56K	1/3W	
R10	RD0455	8.2K	1/3W		R34	RD0464	1.5K	1/3W	
R11	RD0445	56K	1/3W		R35	RD0448	33K	1/3W	
R12	RD0447	39K	1/3W		R36	RD0465	1.2K	1/3W	
R13	RD0452	15K	1/3W		R37	RD0444	68K	1/3W	
R14	RD0449	27K	1/3W		R38	RD0444	68K	1/3W	
R15	RD0449	27K	1/3W		R39	RD0455	8.2K	1/3W	
R16	RD0449	27K	1/3W		R40	RD0450	22K	1/3W	
R17	RD0450	22K	1/3W		R41	RD0450	22K	1/3W	
R18	RD0450	22K	1/3W		R42	RS 5028	1.2K	1. W	
R19	RD0455	8.2K	1/3W		R43	RD0447	39K	1/3W	
R20	RD0450	22K	1/3W		R44	RD2578	680	1/2W	
R21	RD0455	8.2K	1/3W		R45	RD2588	1.8K	1/2W	
R22	RD0457	5.6K	1/3W		R46	RD2588	1.8K	1/2W	
R23	RD2586	1.5K	1/2W		R47	RD0466	1 K	1/3W	
R24	RD0452	15K	1/3W			<u> </u>			

# PD-375 PD-375

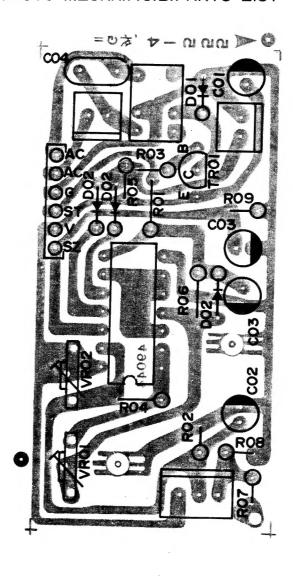
## PB-1373-2 PARTS LIST



## PB-1373-4 PARTS LIST



## FULL-AUTO MECHA.P.C.B.PARTS LIST

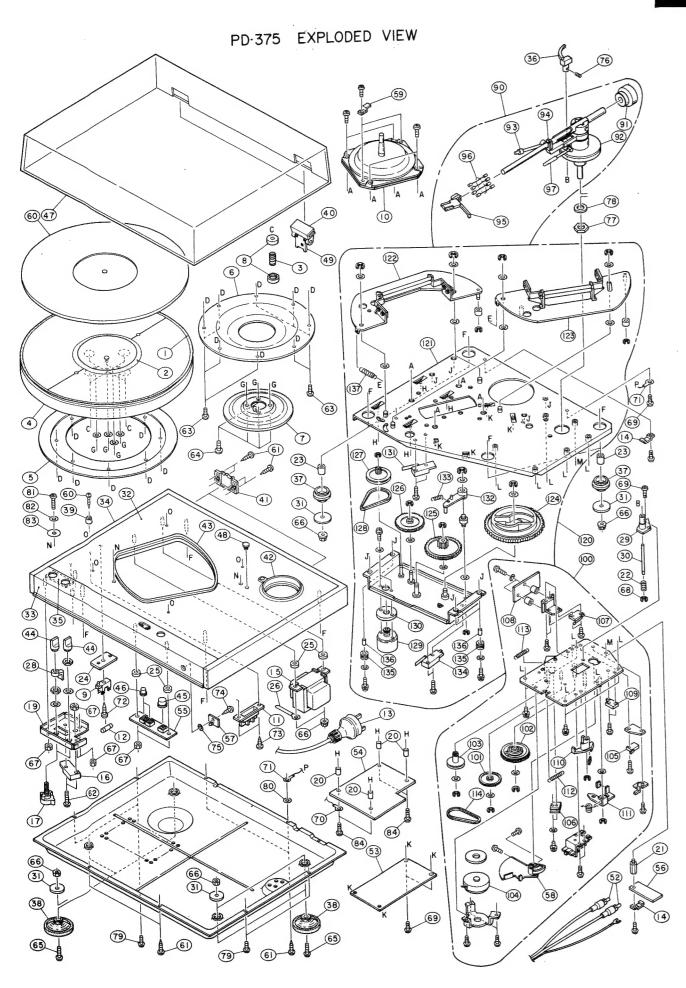


Symbol No.	Stock No.	Description .
(Switc	h)	
SW01	SP0190	Start Cut
SW02	SP0190	V.D.S. On
SW03	SP0190	V.D.S. Off

Symbol No.	Stock No.	Description
110.	140.	
(L.E.D	.)	
D09	TD0196	SLR-30UR

Symbol	Stock	Deg	cription	
No.	No.	Des		
(Trans	istor)			
TR01	TR0087	2SA1 01	5	
(Diode	)			
D01	TDQ0504	10D-1		
D02	TD5012	1S953		
(Semi-	Fixed Res	sistor)		
VR01	RTQ0004		3	
VRO2	RTQ0004	100K	В	
(Carbon	n Resisto	or)		
RO1	RD0043	1 K	1/4W	
R02	RD0023	39K	1/4W	
R03	RD0030	10K	1/4W	
RO4	RD0025	27K	1/4W	
R05	RD0017	100K	1/4W	
R06	RD0011	330K	1/4W	
RO7	RD0043	1 K	1/4W	Ì
R09	RD0011	330K	1/4W	
(Elect	rolytic	Capacit	or)	
C01	CE0819	33uF	16WV	
C02	CE0854	10uF	50WV	
C03	CE0853	4.7uF	50WV	
(Mylar	Capacito	or)		
CO4	CQ0013	0.022u	F 50WV	
(I.C.)				
	TC0140	TC4011	BP	
(Relay	)			
		OUC-S-	112D	

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Exploded View Parrts List

		Exploded view i			
Symbol No.	Stock No.	Description	Symbol. No.	Stock No.	Description
1	UN1031-E	Sealing Pad (out)	62	YAA30A18	Binding 3x18
2	UN1031-E	Sealing Pad (in)	63	YAA30A04	Binding 3x4
				YAA40C08	Binding 4x8 BK
3	UN1039	Coil Spring	I r	YAA40A12	Binding 4x12
4	UN1254	Turn Table			Flange Nut B-5
5	UN1255	Sucking Core		YNKO40A	
6	UZ1257	Sucking Plate		YNKO30A	Flange Nut B-6
7	UZ1292	Roller Plate	68	YWJ025C	E Ring 2.5
8	WZ1154	Spring	69	YJB30A06	Bind Tapping 3x6
9	AH0016	Fuse Holder (UZ)	70	YZBO3OH	Earth Lug
,	AH0019	Fuse Holder (AK, AG)	71	YZB040H	Earth Lug
4.0		DD Motor PHM6002P-01	72	YCG31A13	Round Tapping 3.1x13
10	AM1008				Round Tapping 3.1x10
11	AT0069	Terminal Plate	73	YCG31A10	
12	BF0072	Fuse 0.3A (UZ)	74	YCG27A08	Round Tapping 2.7x8
	BF0201	Fuse 0.1AT (AZ)	75	YWZ030W	Fiver Washer 3
	BF0217	Fuse 0.08 AT (AG, AK)	76	YCD26C04	Allen Fex. Set 2.6x4
13	BK0018	AC Cord (U)	77	YND120A	VR. Nut 12PM
' /	BK0022	AC Cord (AK)	78	YWA120A	Flat Washer 12VP
		AC Cord (AG)	II .	YAA30C06	Binding 3x6 BK
1 /	BK0023			YWEO40M	External Lock Washer
14	BZ0023	Cord Clamp	1		Binding 4x20
15	PT2546	Power Trans(U)	81	YAA40A20	
	PT2548	Power Trans (AK,AG)	82	YWA040T	Flat Washer 4
16	SP0191	GV Switch	83	MH1004	Caution Seal
17	SR01 58	Rotary Switch	84	YAA30A06	Binding 3x6
18	UE1112	Bottom Plate	90	WZ1192	Tone Arm Ass'y
19	UR1 31 9	Bracket	91	WZQ0018	Weight Ass'y
20	US0003	P.C.B. Stand	92	WDQ0010	Arm Base
			93	WZQ0015	IFC Ass'y
21	US5023	Stand	94	WZQ0016	Arm Rest Clip
22	UU1 041	Lifter Spring		-	Head Shell
23	UW1131	Insulator Column	95	WZ1191	1
24	UW1139	Spacer	96	WZQ0018	Cartridge Wire
25	UW1140	Spacer	97	WZQ0017	Arm Lifter Lever
26	UZ1114	Bind Bracket	100	UZ1285	Full Auto Mecha Ass'y
28	UZ1282	Switch Lever	101	U0Q0006	Gear
	i	Lift Bearing	102	U000007	Cam Ass'y
29	UZ1283		103	BXQ0001	Pulley
30	UZ1284	Lift Shaft	11		AC Motor Ass'y
31	UZ1286	Insulator Spacer	104	AMQ0102	
32	WA1231	Aluminum Panel A	105	SPQ0008	Micro Switch
33	WA1232	Aluminum Panel B	106	APQ0010	Sensor Ass'y
34	WB1093	Cabinet	107	SPQ0004	Micro Switch
35	WD1135	Escutcheon	108	APQ0010	P.C.B. Ass'y
36	WZ1145	Lifter	109	SPQ0005	Micro Switch
		Main Insulator	110	0000008	Manual Selector Ass'y
37	WZ1148		111	U0Q0009	Brake Lever Ass'y
38	WZ1189	Cabinet Insulator	III .		Tension Spring
39	UW1137	Spacer	112	UUQ0001	1 0
40	UZ1277	Hinge	113	UUQ0002	Tension Spring
41	UZ1278	Hinge Holder	114	UZQ0003	Belt 288
42	WD1134	Escutcheon	120	UZ1279	Mecha. Chassis Unit
43	WE1 098	Edge Protector	121	UAQ0002	VDS Base Plate Ass'y
44	WJ1093	Knob	122	U0Q0013	Charge Lever Ass'y L
	1	Knob (Start/Cut)	123	U0Q0014	Charge Lever Ass'y R
45	WJ1152	Knob (V.D.S. ON/OFF)	124	U0Q0010	Main Cam Gear
46	WJ1154		125	U0Q0010	Gear 3
47	WZ1147	Dust Cover			
48	WZ1158	Cap	126	-	Gear 4
49	WZ1178	Bushing	127		Pulley
51	WZ1160	Record Sheet	128		Belt 375
52	BK0063	Arm Cable	129		Motor (VDS)
	AM1 008	Motor P.C.B.	130		Motor Cushion
53			131		Micro Switch A
54	P1373-1	PB1 373-1	132		Switch Holder
55	P1373-2	PB1373-2	11	1	
56	P1373-3	PB1373-3	133		Tension Spring
57	P1373-4	PB1373-4	134		Micro Switch B
58	UQQ0005	Restor Lever Ass'y	135	UNQ0002	Cushion
59	UR1341	Motor Holder Bracket	136	1	Column 375
	1		137	1 -	Charge Lever Spring
	VCCCOLCA	Dound Tenning 2 /17 11			
60	YCG24C10	Round Tapping 2.4x10 Round Tapping 3.1x10	171	000004	omigo in the property

## Remarks:

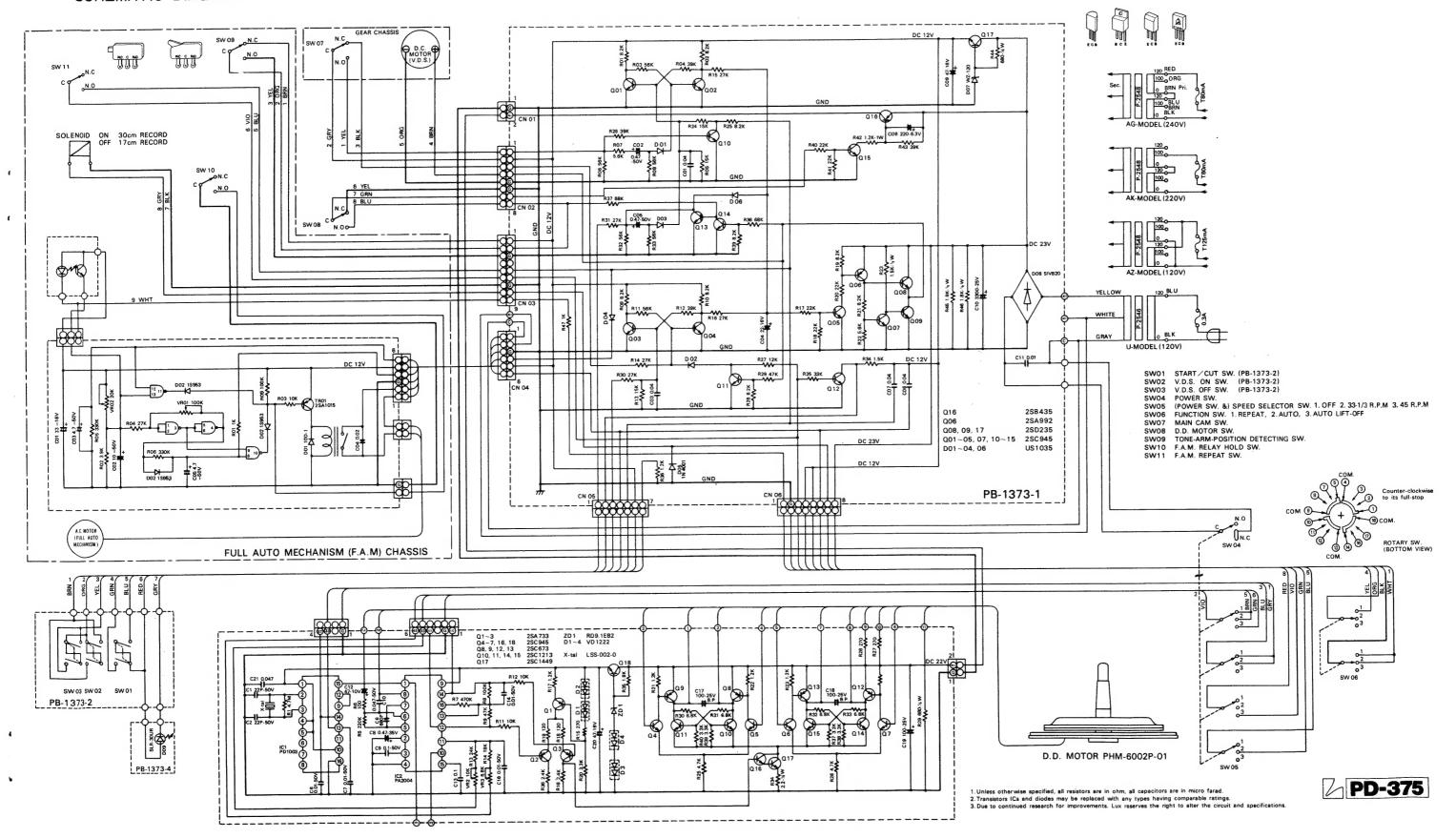
U....120V For North America.

AK...220V (With Line Voltage Selector) For Europe, South East Asia.

AG...240V (With Line Voltage Selector) For England, Australia.

AZ...120V (With Line Voltage Selector) For North America, South Asia, East Asia.

## SCHEMATIC DIAGRAM



## **SPECIFICATIONS**

(Phono Motor Section) \*Driving System: Direct-Drive System DC-servo brushless & slotless quartz-locked motor \*Moter: \*Turntable Platter: 30cm aluminiumdie-cast with built-in VDS pump (2.5 kgs) 33-1/3 rpm, 45 rmp (2-speed) \*Rotation: \*Adjustable Range of Rotation: better than 70dB(DIN B) \*S/N Ratio: \*Wow & Flutter: no more than 0.03% W.R.M.S. (Tonearm Section) \*Tonearm: Straight Arm of static balance type \*Effective Length: 230mm +2°121 1° 301 \*Tracking Error: \*Overhang: 16mm \*Cartridge Weight: 5g~10g \*Cartridge Height: 16mm~19mm (by use of spacers) \*Stylus Pressure: 0~3g (direct reading) \*Accessories: Anti-skate adjustment (Addtional Features) \*Dust Cover: Detachable with semi-freestop hinge \*Automatic Function: Auto-Lead-In(Auto Start), Auto-Repeat, Operation Mode Selector(repeat, auto, auto-lift-off), Start/Cut Button (General) \*Power Consumption: 10W(CSA rated) 438 (W) x 165 (H) x 365 (D) mm \*Dimensions:  $(13.9" \times 6.4" \times 14.6")$ 10.5 kgs (23.1 lbs.) \*Weight: Net 12.0 kgs (26.4 lbs.) Gross

Specifications and appearance design subject to change without notice.